



APEC
2024

LONG BEACH
CALIFORNIA
CONVENTION CENTER

February 25th - 29th

Emulation of Plasma Load Reactances by Saturation Control of Low-Permeability Inductors

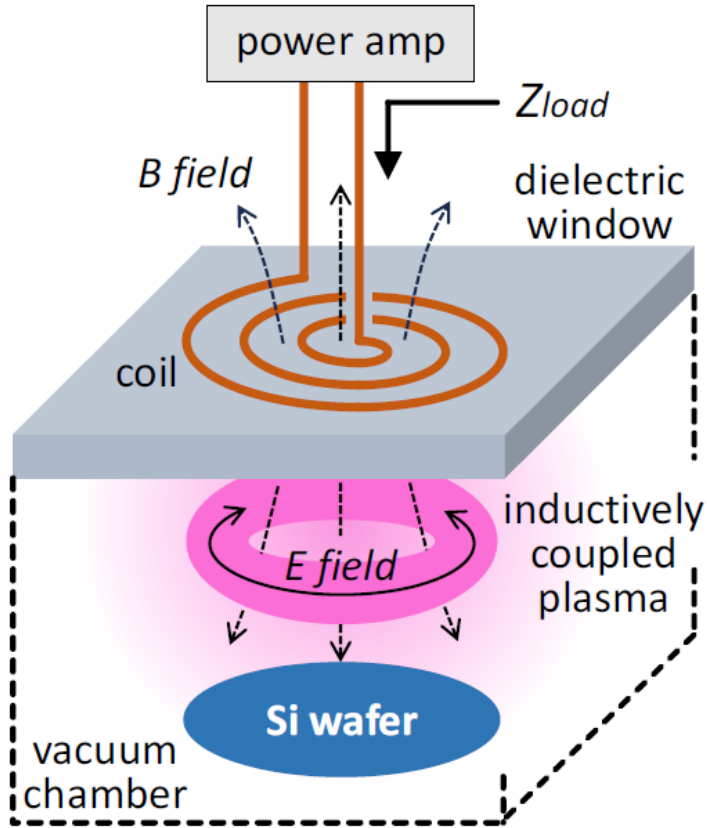
Darshan Tagare - Arizona State University

Sanghyeon Park - Lam Research Corporation

Mike K. Ranjram - Arizona State University

Advanced RF Generator Have Complex Behavior

- Dr. Sanghyeon Park (our collaborator from Lam) sums up the project very well:



Good old days

plasma needed : 

RF power : 

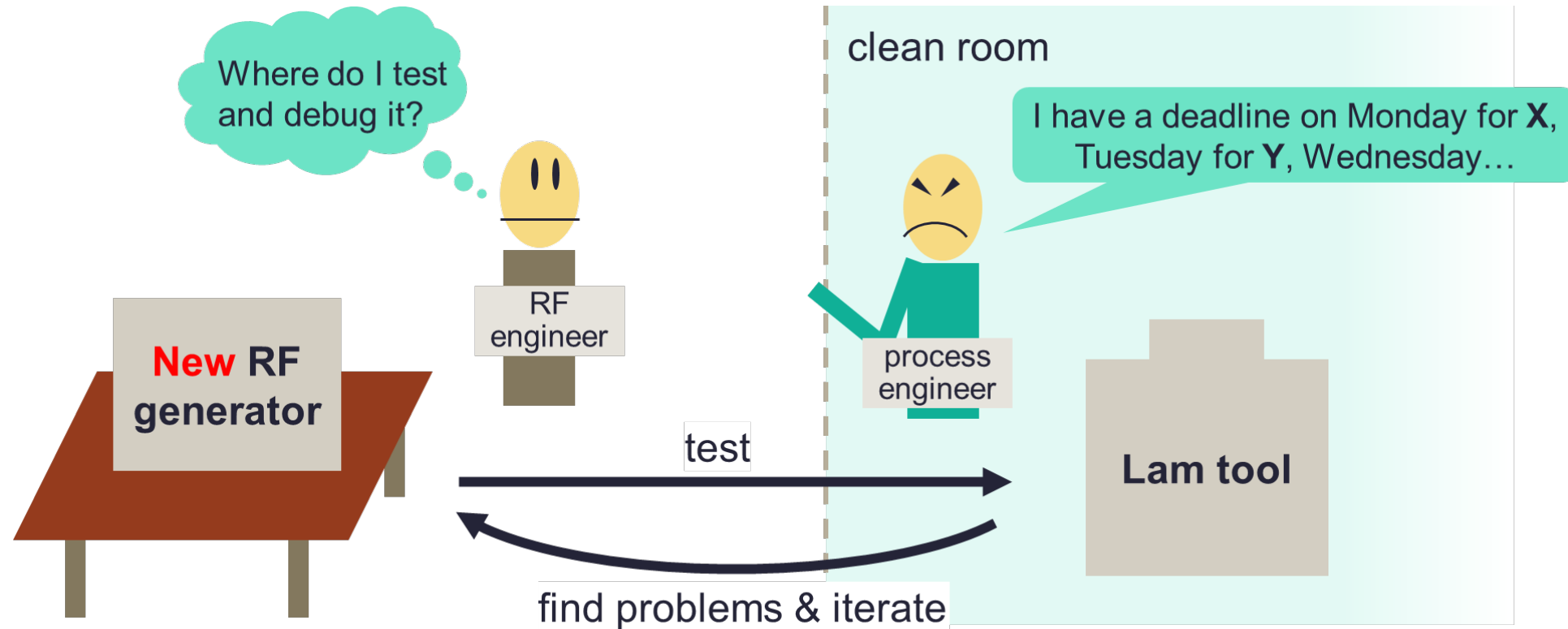
These days

plasma needed : 

RF power : 

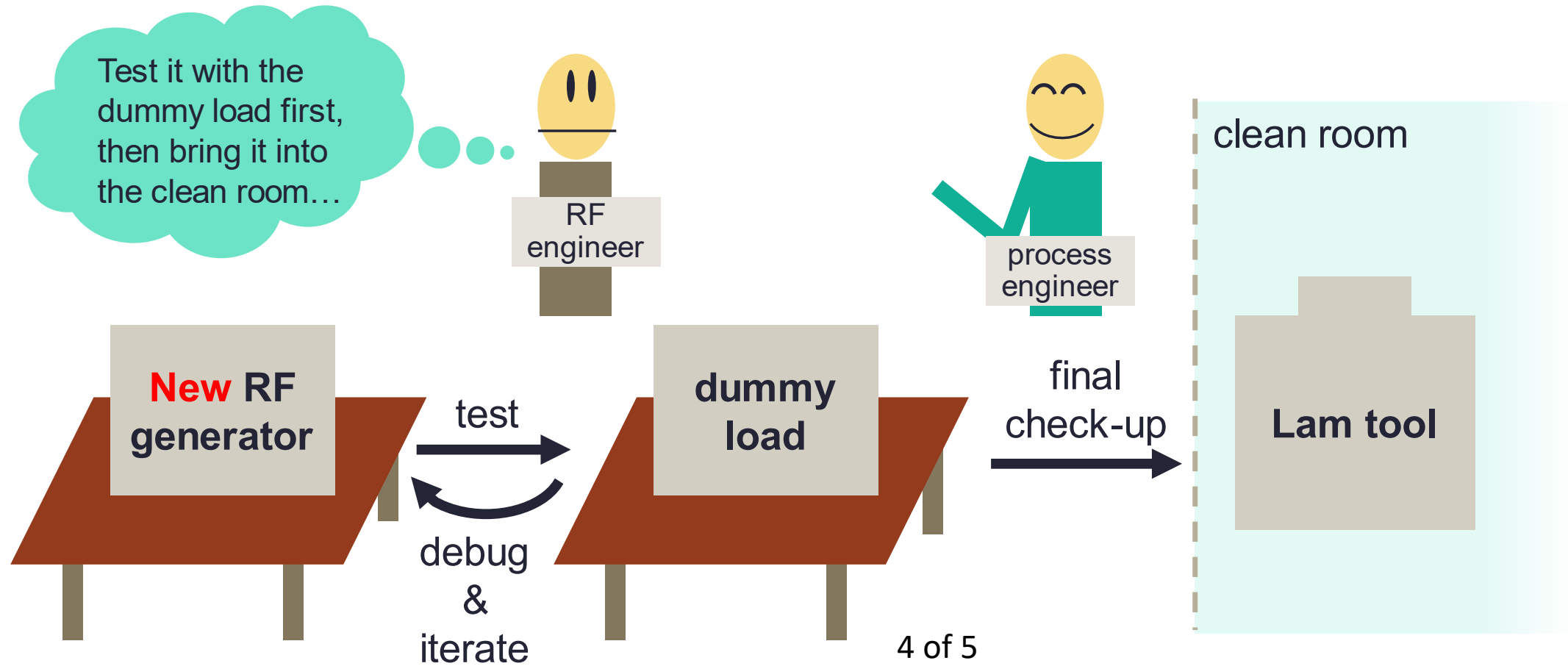
Creates a need for
advanced RF
generators

Problem: Validation and Debugging is Complicated



- New RF generator: miniaturized, lower cost, faster, etc.
- To validate a new RF generator, must install it in a real tool and run it.
- Tool time is a rare commodity, process engineers have immediate deadlines, RF engineers may need weeks/months to iterate and root out all the issues.

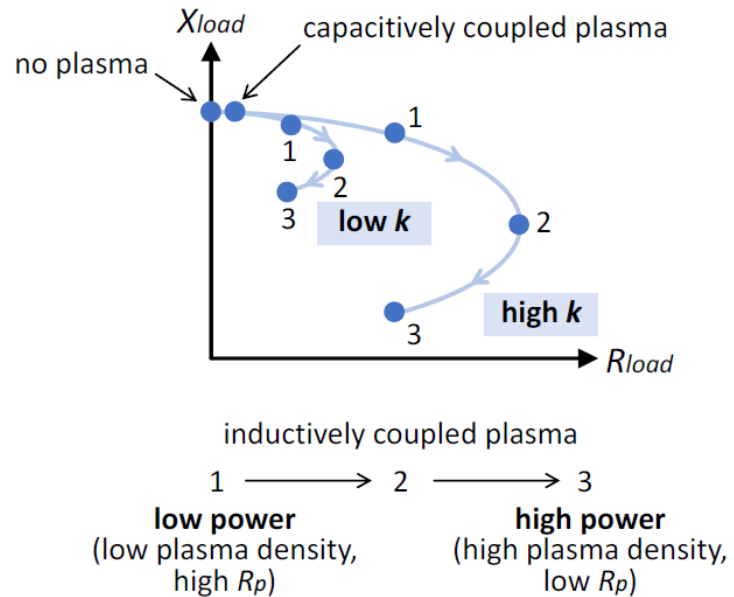
Solution: A Dummy Load that Can Mimic Plasmas



- Programmable load allows consistency and speeds up debugging.
- Ideally, dummy load *perfectly* matches the plasma, but even a close representation is useful.

Modeling Inductively-Coupled Plasmas (ICPs)

Plasma impedance is highly dynamic



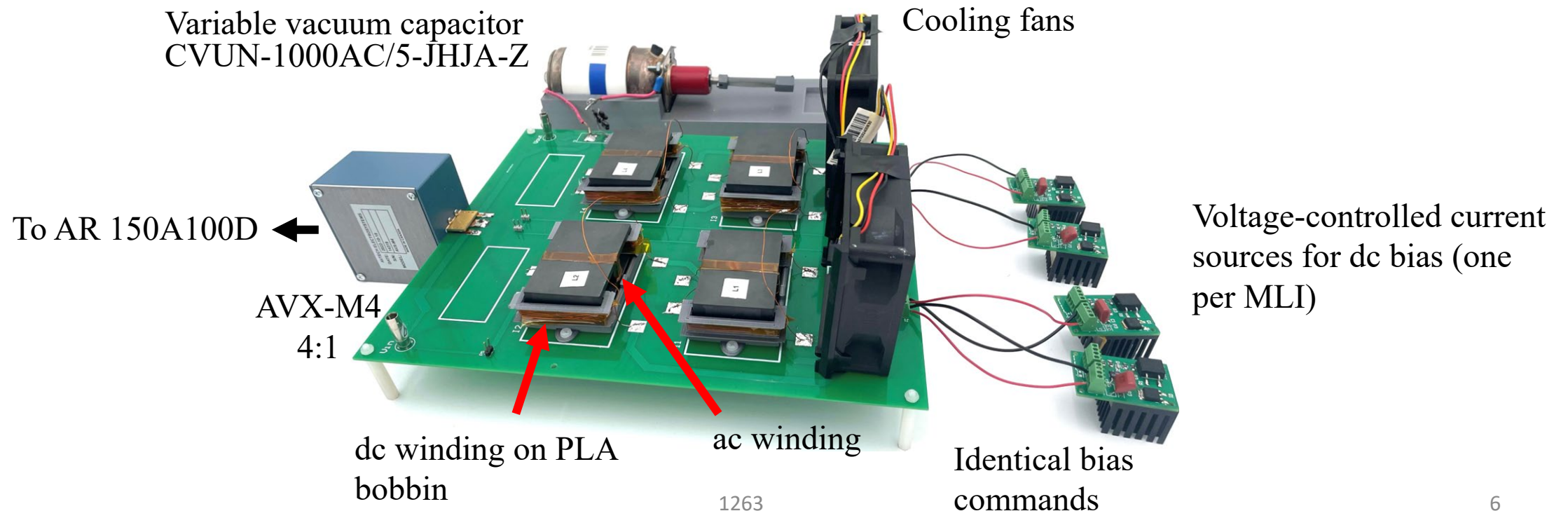
Time varying Inductance and Resistance

Dummy load needs:

- Variable resistance (a known unknown, e.g., fixed + controlled resistors).
- Variable reactance – an unknown unknown - 20% variation in $100\mu s$.

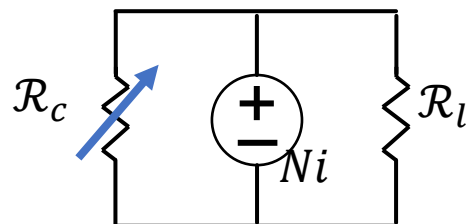
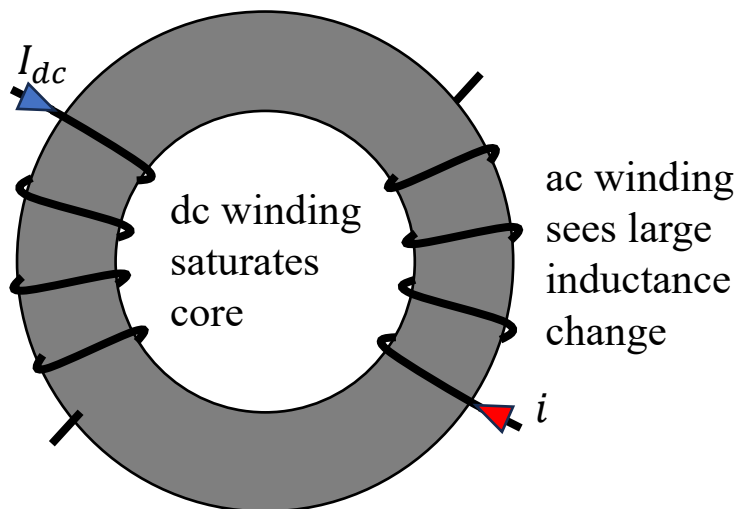
Our Contribution: HF, Low Permeability, Saturable Inductor Array Design Approach

- Dummy load: $2.5\mu H$ inductor carrying $20A_{pk}$ at 13.56MHz.
- Too large for a single off-the-shelf core, so use a modular design (series/parallel inductors).



A Rich History of Saturation Control

Saturable Reactor



$$L = N^2 \left(\frac{1}{\mathcal{R}_c} + \frac{1}{\mathcal{R}_l} \right)$$

Pros:

- Large inductance due to no gap.
- Large inductance change due to full saturation.

Cons:

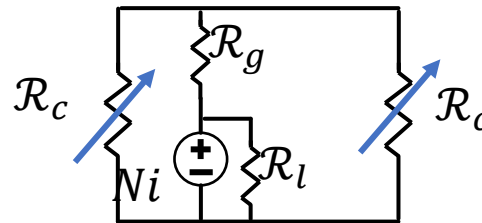
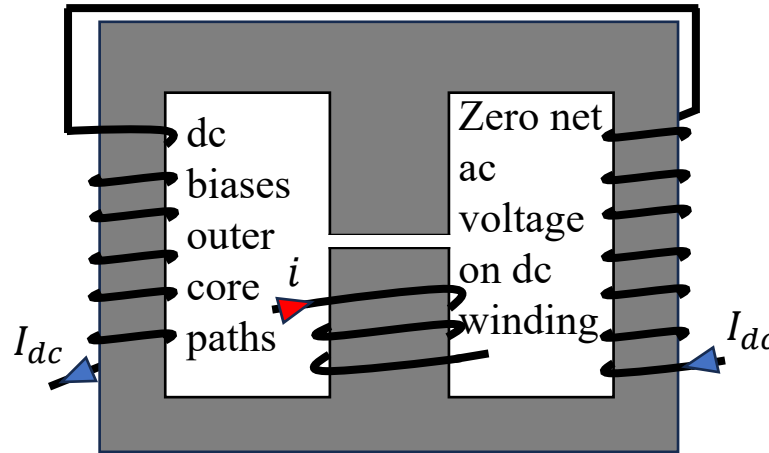
- DC windings may see large inductance.
- AC and DC windings are directly coupled (can be mitigated in a multi-core approach).
- Need to ensure small-signal excitation near saturation to avoid distortion.

A Rich History of Saturation Control

Pros:

- Mitigates AC to DC coupling.
- Can be used with gapped construction.

Multi-Leg Inductor



$$L = N^2 \left(\frac{1}{\frac{R_c}{2} + R_g} + \frac{1}{R_l} \right)$$

Cons:

- DC winding may see large inductance.
- E-cores (currently) uncommon for high-frequency FR67 core material.
- Lower inductance variation if a gap is used.

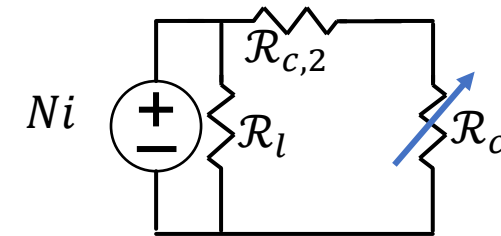
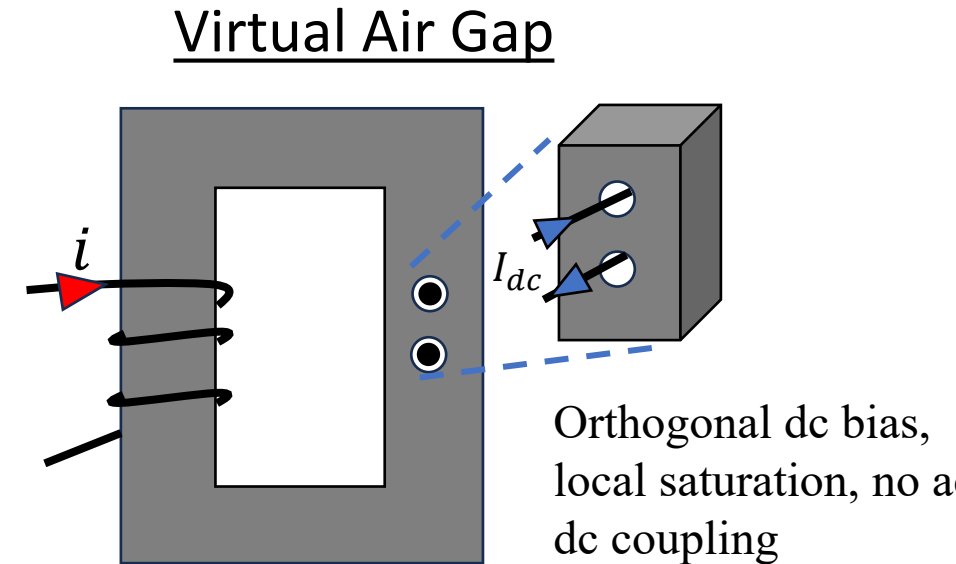
A Rich History of Saturation Control

Pros:

- Total decoupling of AC and DC systems.
- Low inductance on DC windings.

Cons:

- Hard to construct.
- May yield low inductance change.



$$L = N^2 \left(\frac{1}{R_c + \mathcal{R}_{c,2}} + \frac{1}{\mathcal{R}_l} \right)$$

Research Questions

Are saturable inductors viable for emulating the reactance of a plasma load?

That is, can we:

1. Achieve $\sim 20\%$ inductance change with reasonable bias circuitry?
2. Ensure linearity of the inductor under saturation?
3. Achieve a dynamic inductance response at $100\mu s$?
4. Show that a saturable inductor can be modularly scaled?

Key Difference: HF Materials Have Low Permeability

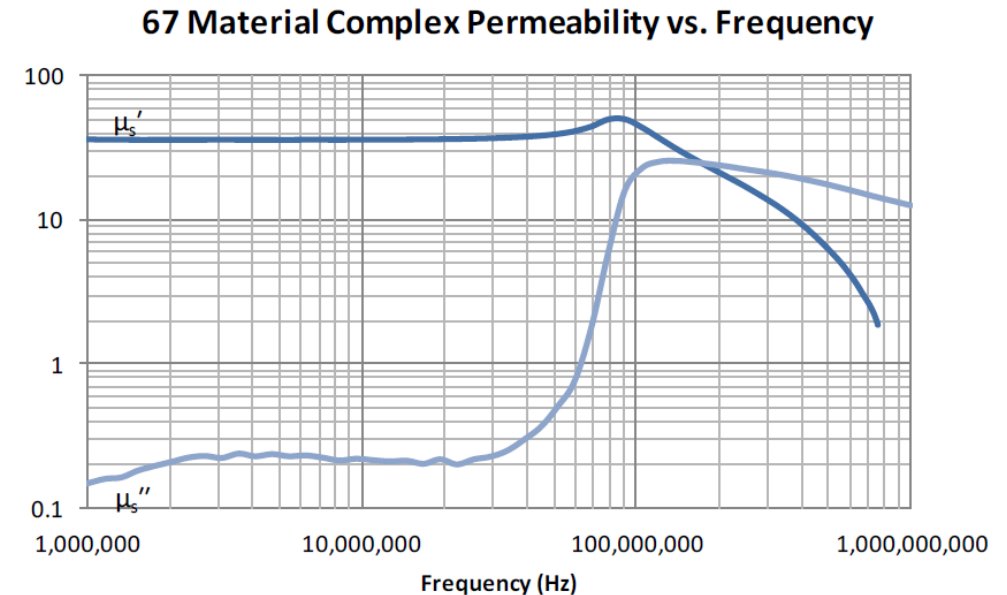
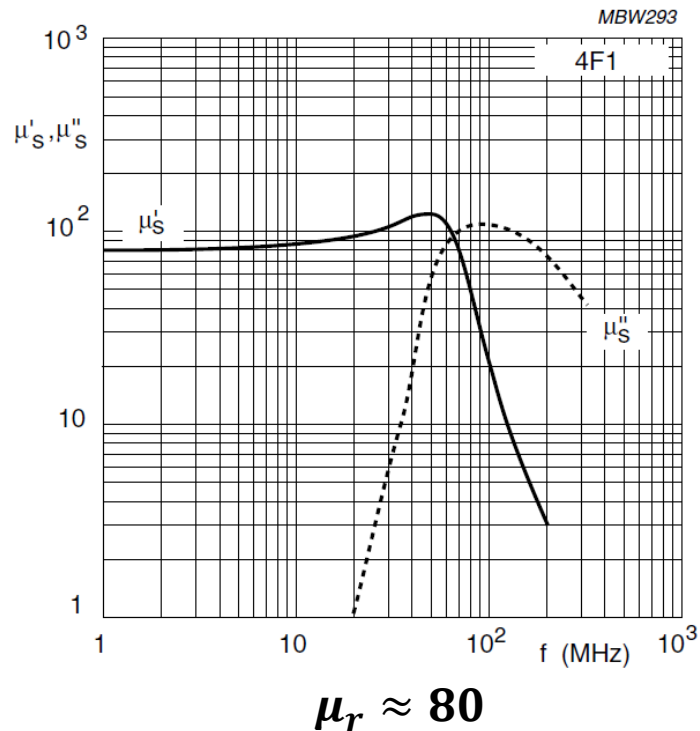
We need a magnetic material with:

- Inductive behavior at 13.56 MHz.
- Strong susceptibility to saturating fields.



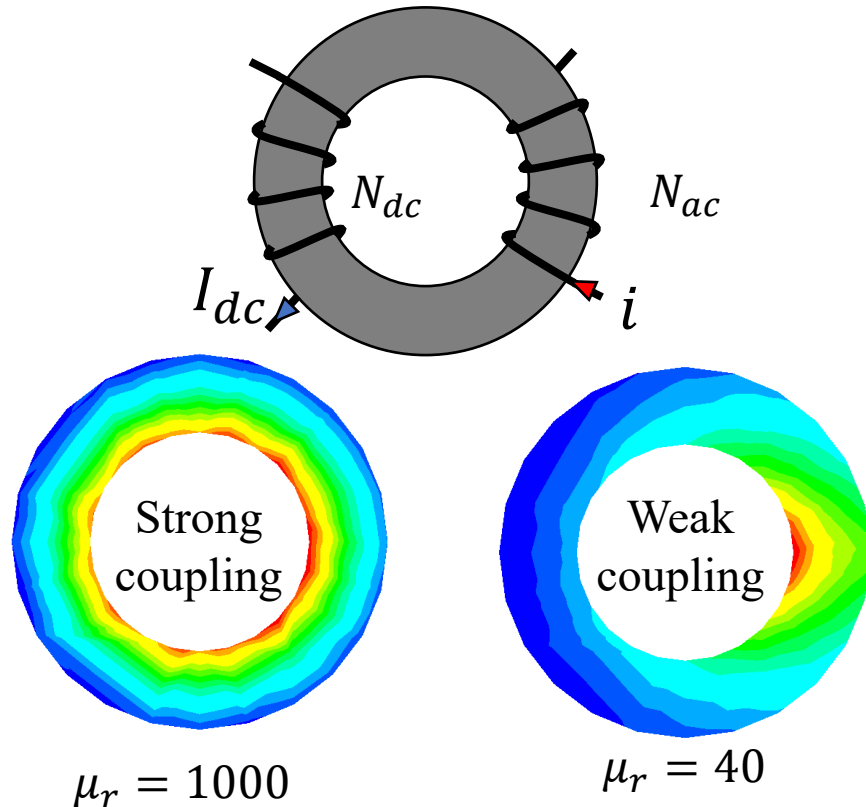
Options:

NiZn ferrites:
Ferroxcube 4F1, Fair-rite FR67



Low Permeability Changes Saturation Strategies

Saturable Reactor



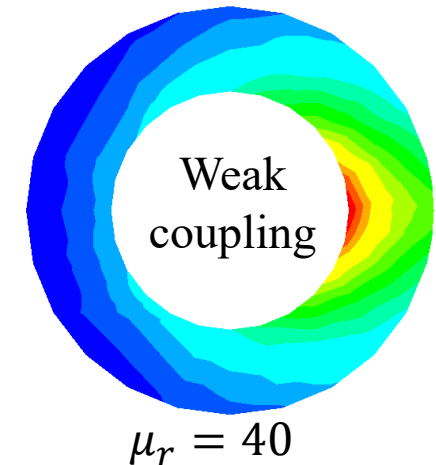
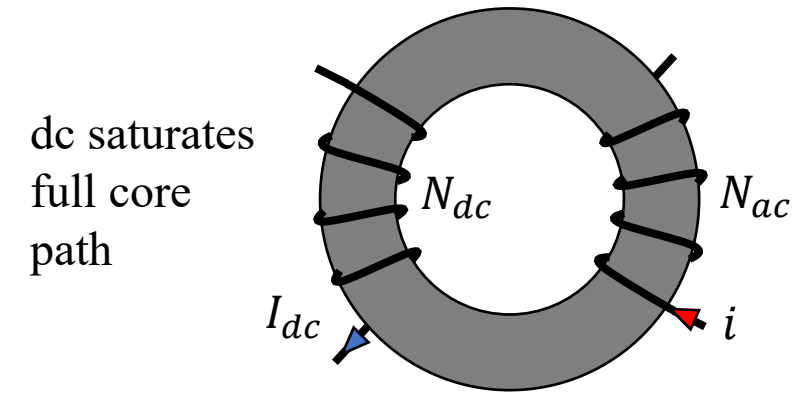
- Saturation strategies mimic virtual air gap!
- Likely to be linear; unlikely to get big inductance change (but 20% isn't very big).
- We have adopted a multi-legged approach. (Please refer to the accompanying paper for a comprehensive analysis of the tradeoffs and selection criteria).

Low Permeability Challenges

1. Weak coupling and localized saturation

- These can be very leaky designs.
- Leakage inductance difficult thing to predict “on paper” (simple magnetic circuit analysis not appropriate).
- Inductance is a strong function of the ac winding geometry.
- Saturation is a strong function of the dc winding geometry.

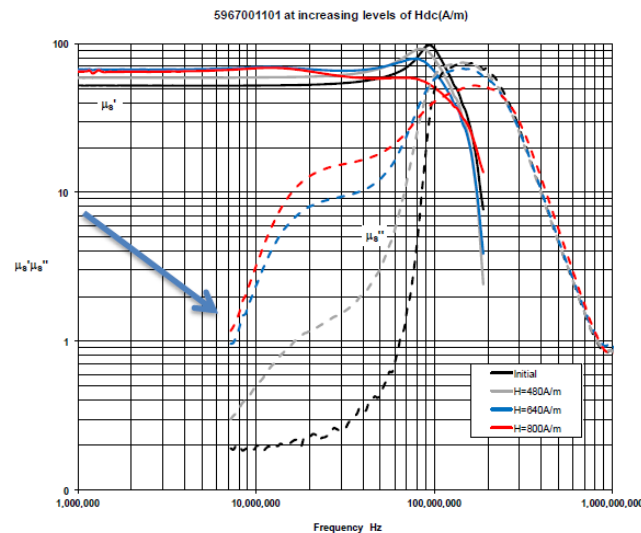
Saturable Reactor



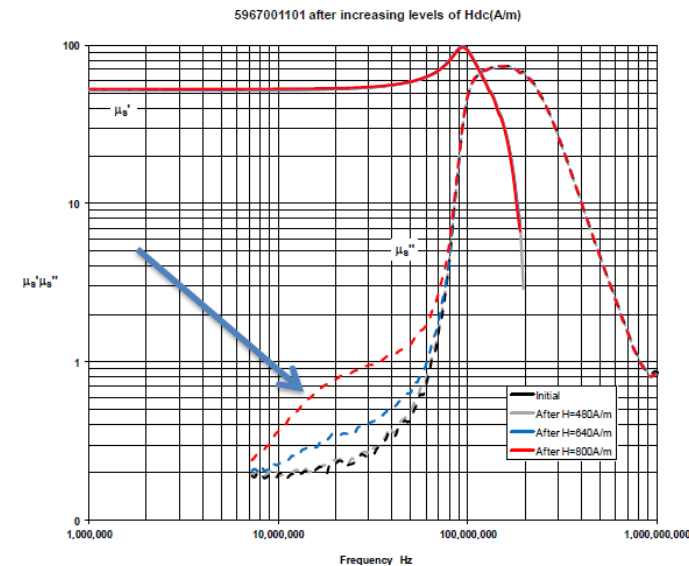
Low Permeability Challenges

2. Perminvar characteristics

- FR67 has properties that change under high magnetic fields.
- Action:** “pre-bias” cores by subjecting them to field intensity > 800 A/m



Effects of DC bias

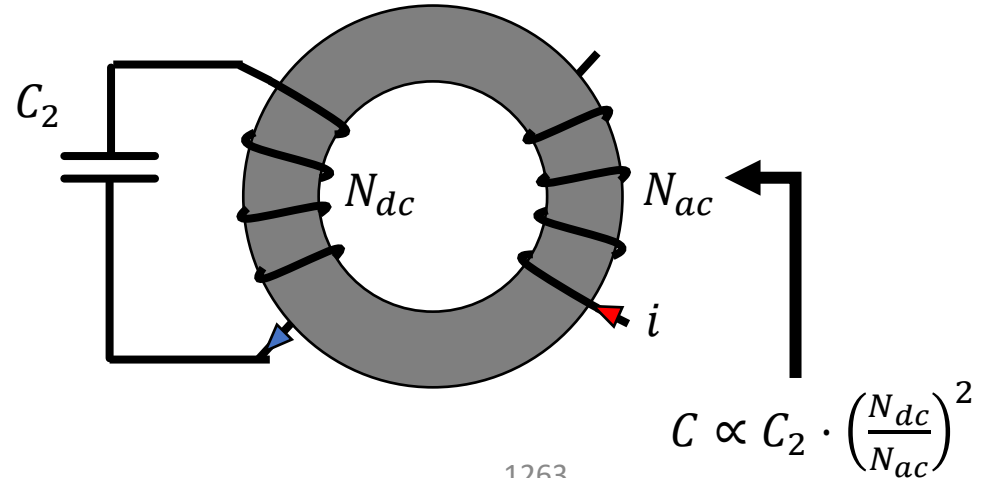


- If a part is exposed to a DC bias that is too high, there is an irreversible changes to the losses.

Low Permeability Challenges

3. Self-resonance

- We target high inductance ($2.5\mu H$) – a small effective capacitance (55.1pF) can yield 13.56MHz resonance.
- In particular, capacitance across dc windings can be problematic.
- **Action:** Minimize dc turns count
But recognize that parasitics are inherently difficult to model.



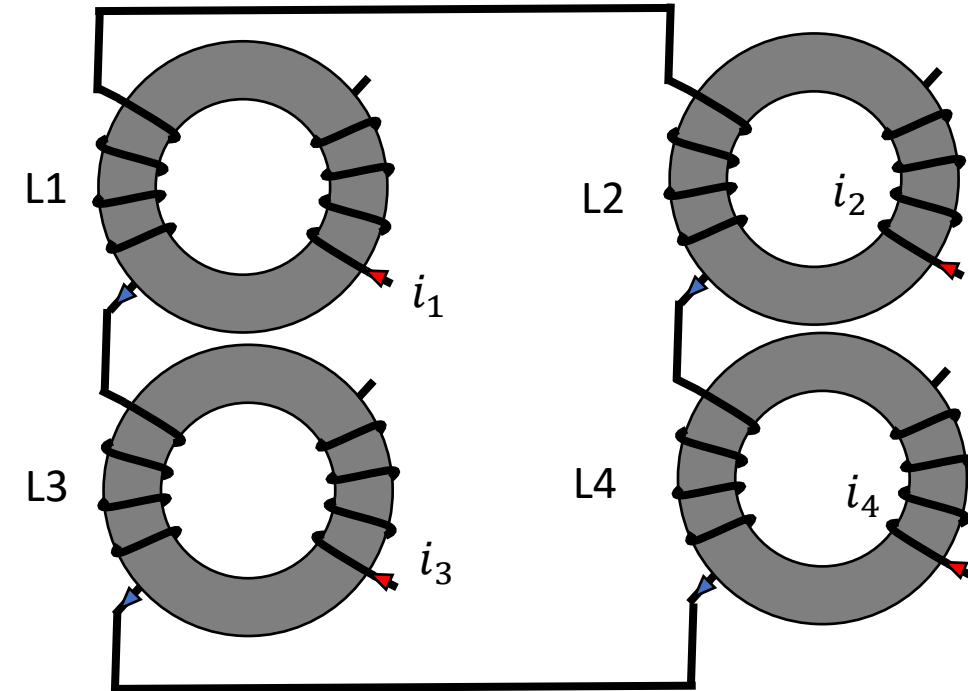
Low Permeability Challenges

4. Un-gapped constructions

- Want to maximize inductance variation, so avoid gap.
- Incur the typical challenges, permeability depends on: temperature, lot-to-lot variation.
- **Action:** Allow individual biasing of cores in an array.

Design Approach?

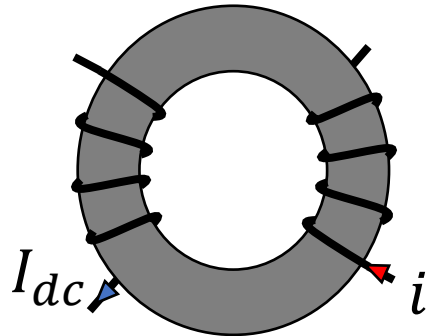
- These Low permeability challenges impede a design “on paper”, without experimental characterization.
- So, forgo an analytical design framework and develop an “experiment in the loop” design approach, to show the concept has legs.



Design Approach

1. Select a core material and core set
Use the largest available cores to minimize the size of the array.
2. Design the ac turns
Start with A_L from datasheet, measure, then (likely) decrease N_{ac} .

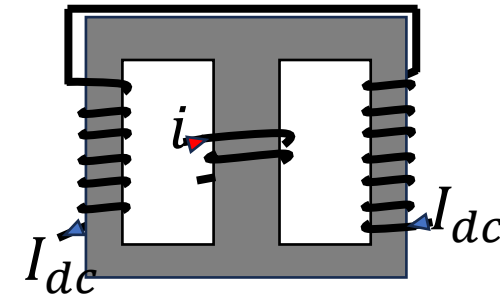
T61/35.5/12.7, FR67



Datasheet: $55 \text{ nH}/N^2$

Designed value $N_{ac} = 5$
 $125 \text{ nH}/N^2$

E58/11/38, 4F1

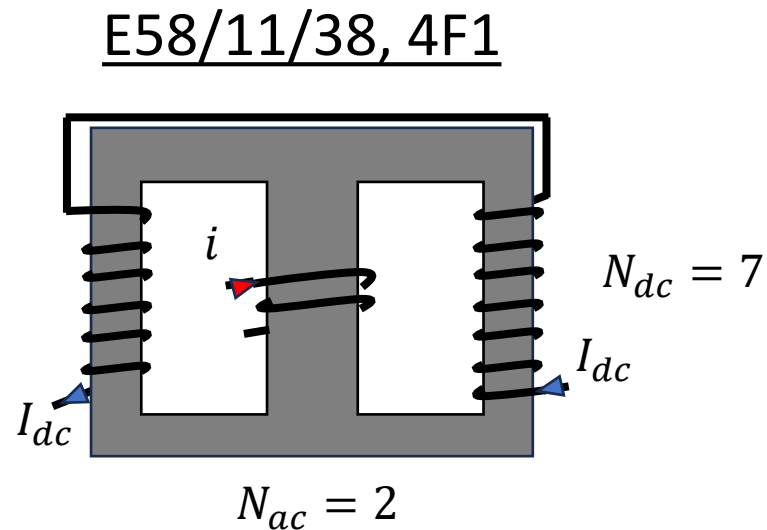


Datasheet: $450 \text{ nH}/N^2$

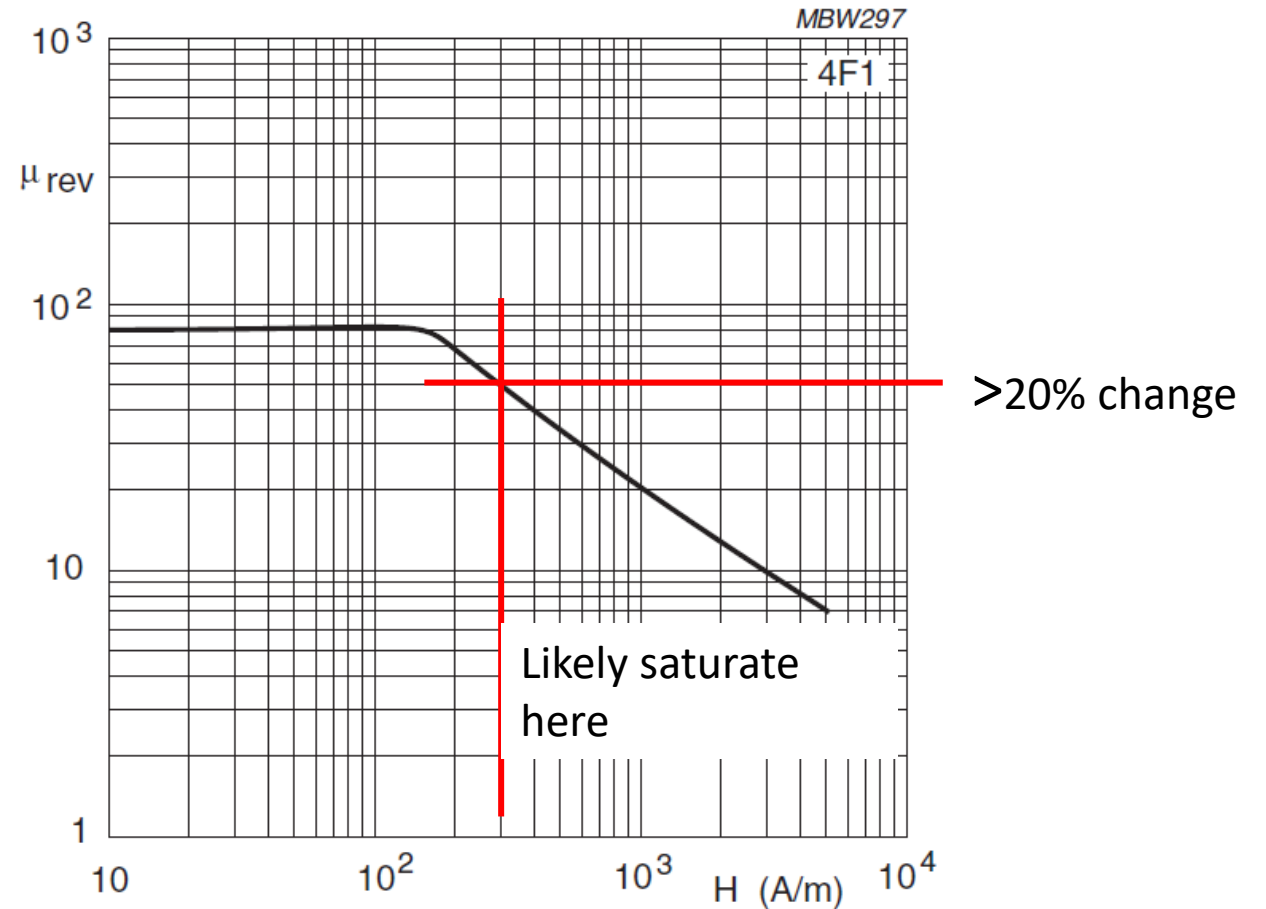
Designed value $N_{ac} = 2$
 $650 \text{ nH}/N^2$

Designing the dc turns

3. Then, use a single magnetostatic ANSYS simulation to determine dc biasing MMF applied by dc turns (e.g., $H_{bias} = 18N_{dc}I_{dc}$).



- Start with manufacturer bias information (if available)



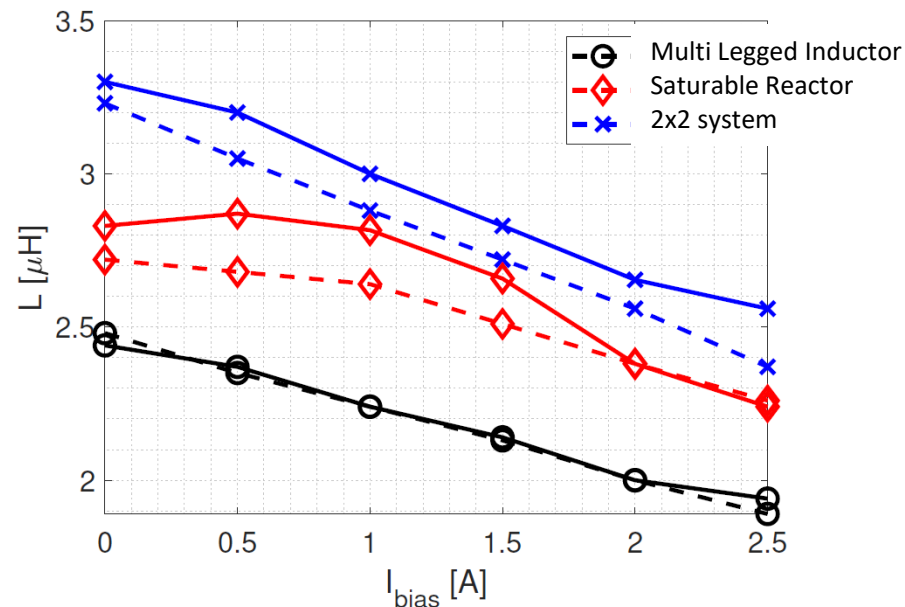
Small signal and Large signal testing

4. Small signal testing

Use an impedance analyzer to measure dc bias response. Target 0-2.5A for ease of bias implementation.

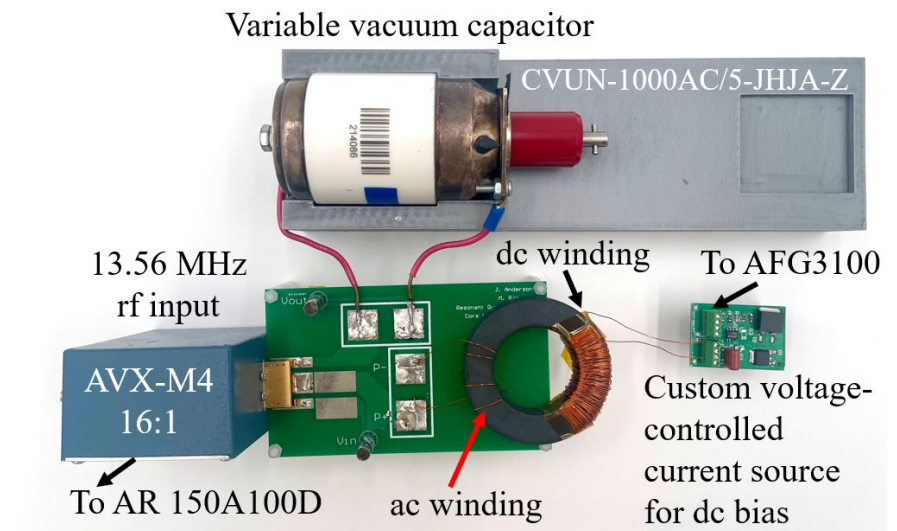
5. Large signal testing

Ensure the linearity of the inductor under saturation with large signals applied to it.



Solid line- Large signal

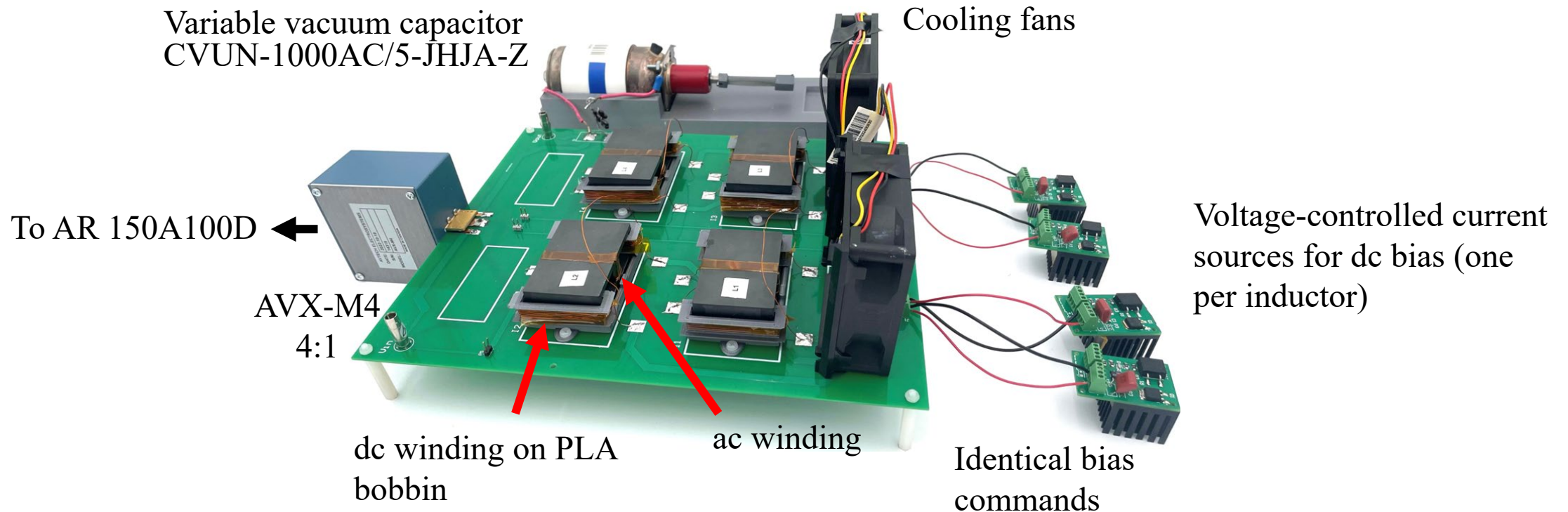
Dashed line – Small signal



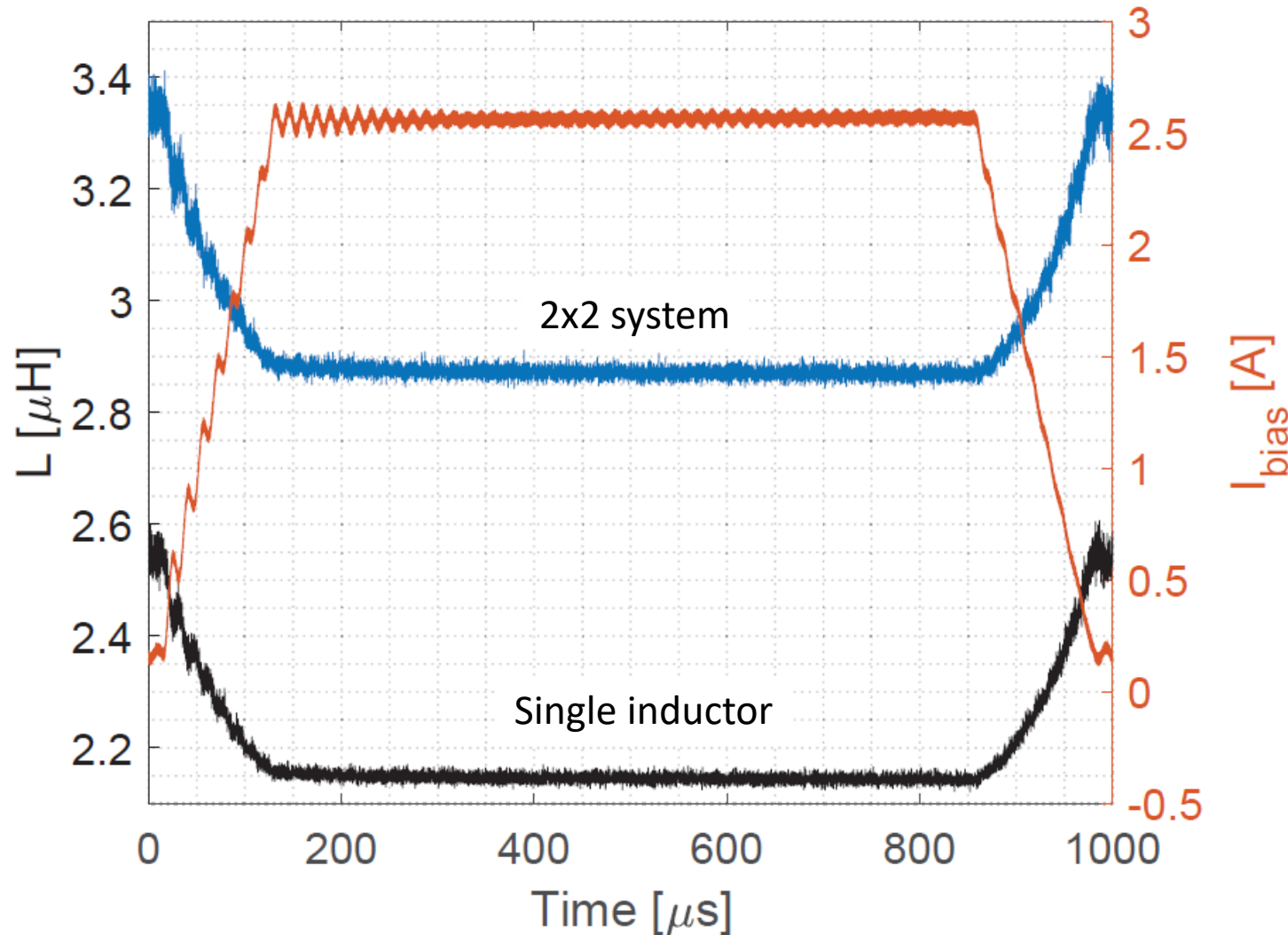
Large signal setup (Using series L and C resonance to calculate core loss and inductance value)

2 x 2 Variable Inductor with Multi Leg Approach

- Each inductor is individually controlled through its dedicated bias circuit.



Achieves 20% L Variation in 0.1 ms



- No special coordination between different array elements, they all receive the same bias command.
- Large signal data – no non-linearity observed.
- Limit is slew rate of current source .

Contributions and Conclusions

1. Presented plasma generation and modeling overview.
2. Incorporated low permeability saturation control into established high permeability methods.
3. Outlined Design approach for creating low permeability variable reactors with DC bias control.
4. Shared small and large signal testing outcomes, including dynamic inductance change and core loss data, confirming inductor suitability for plasma emulation systems.
5. Experimentally validated a downscaled 2x2 inductor prototype.